Review Form 1.6

Journal Name:	Journal of Scientific Research and Reports
Manuscript Number:	Ms_JSRR_84880
Title of the Manuscript:	Droop Control of Inverter Interfaced Distributed Generation
Type of the Article	Original Research Article

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of 'lack of Novelty', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(https://www.journaljsrr.com/index.php/JSRR/editorial-policy)

PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
<u>Compulsory</u> REVISION comments	What are the necessary equations involved in designing of the droop control The author has to provide the elaborated content of droop control structure.	This/fiel reedback field)
	2. Can we use fuzzy logic controllers in place of PI controllers for faster response and accuracy?	
	3. What is the value of power factor that is considered in the calculation of active and reactive power?	
	4. What are the values of droop coefficients considered in the P-f and Q-V characteristics?	
	5. What is the maximum step load that we can apply for the proposed droop control logic?	
	6.present the control strategy by taking any power system Network	
Minor REVISION comments	Include more number of references for literature review	
Optional/General comments	More Results should include with various types of load like inductive and resistive also	

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PART 2:

		Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript?	(If yes, Kindly please write down the ethical issues here in details)	

Reviewer Details:

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