

Review Form 1.6

Journal Name:	Current Journal of Applied Science and Technology
Manuscript Number:	Ms_CJAST_85313
Title of the Manuscript:	Design and Simulation of Amphibious Wheel-Foot Composite Mechanism
Type of the Article	Short Research Article

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<https://www.journalcjast.com/index.php/CJAST/editorial-policy>)

PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Compulsory REVISION comments		
Minor REVISION comments	#All the equations should be mentioned in the text article. #Figure 5 should be mentioned in the text of the article #Figure 5 should be mentioned in the text of the article	Thank you very much for your comments. According to your comments, I introduced all the pictures and formulas in the article.
Optional/General comments	General Comments The Title is appropriate for the research. The introduction is well structured and articulated. The methodology is well spelt out for the achievement of the research and also appropriate. The results are well details and discussed properly. The conclusion is well constructed and structured. The listed references need some proper correction	Thank you very much. I have made appropriate amendments to the references according to your comments.

PART 2:

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript? NO	<i>(If yes, Kindly please write down the ethical issues here in details)</i> NO	This paper mainly studies the design and simulation of the wheel-foot composite mechanism of amphibious robot. There are some unreasonable places in this paper, but I have modified these places now.